

ABSTRACT

In the conventional cleaning robot, by mainly using each supersonic waves sensor having a sensing range as $\pm 30^\circ$ in consideration of an appropriate sensitivity, when four supersonic waves sensors are installed at a cleaner main body, a sensing range as 240° is obtained, and accordingly it is impossible to observe surroundings of the cleaner thoroughly. In order to solve the above-mentioned problem, a position information recognition apparatus for a cleaning robot in accordance with the present invention includes a fixed plate installed at a cleaner main body; a main motor fixedly installed at the fixed plate in order to generate a rotational force; a rotational cylinder combined with a rotational axis of the main motor so as to be rotated at a certain angle; and plural position information sensors installed at the rotational cylinder at a certain angle in order to sense surroundings. By installing several supersonic waves sensors performable left/right rotation at regular intervals, observation region can be greatly increased, and accordingly it is possible to improve efficiency by eliminating unnecessary rotational motion of the cleaner main body in position recognition and distance compensation.